

Escola de Ciências e Tecnologia  
Universidade de Évora

## Polymatrix Games and Replicators

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DSABNS

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- ▶ Example

## Lotka-Volterra System

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$\mathbb{R}_+^n = \{(x_1, \dots, x_n) \in \mathbb{R}^n : x_i \geq 0, i = 1, \dots, n\}$  is invariant under (1)

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J. Hofbauer (1981): every LV system in  $\mathbb{R}_+^n$  is orbit equivalent to a replicator system on the  $n$ -dimensional simplex  $\Delta^n$

## Bimatrix replicator

$$\begin{cases} x'_i &= x_i ((Ay)_i - x^t A y) & i = 1, \dots, n \\ y'_j &= y_j ((Bx)_j - y^t B x) & j = 1, \dots, m \end{cases} \quad (3)$$

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$$\begin{array}{c} n \\ m \end{array} \left[ \begin{array}{c|c} n & m \\ \hline 0 & A_{n \times m} \\ \hline B_{m \times n} & 0 \end{array} \right]$$

$(n+m) \times (n+m)$

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$$\begin{array}{c} \begin{array}{ccccc} & n_1 & \dots & n_\beta & \dots & n_p \\ n_1 & [ & & & & ] \\ & A^{1,1} & \dots & A^{1,\beta} & \dots & A^{1,p} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ n_\alpha & A^{\alpha,1} & \dots & A^{\alpha,\beta} & \dots & A^{\alpha,p} \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ n_p & [ & & & & ] \\ & A^{p,1} & \dots & A^{p,\beta} & \dots & A^{p,p} \end{array} \end{array}$$

$n \times n$

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$\sum_{j \in \alpha} x_j (Ax)_j$  represents the average payoff of all strategies in the group  $\alpha$

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( $A^{\alpha,\alpha} = 0, \quad \alpha = 1, \dots, p$ ) replicator eq. for  $n$ -person games



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$$\Gamma_{\underline{n}} := \Delta^{n_1-1} \times \dots \times \Delta^{n_p-1} \subset \mathbb{R}^n$$

$\Gamma_{\underline{n}}$  is parallel to  $H_{\underline{n}} := \left\{ x \in \mathbb{R}^n : \sum_{j \in \alpha} x_j = 0, \text{ for } \alpha = 1, \dots, p \right\}$

## Polymatrix Replicator - Interior equilibria

$$x'_i = x_i \left( (Ax)_i - \sum_{j \in \alpha} x_j (Ax)_j \right), \quad i \in \alpha, \quad \alpha = 1, \dots, p$$

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### Proposition

Given a polymatrix game  $(\underline{n}, A)$ , a point  $q \in \text{int}(\Gamma_{\underline{n}})$  is an equilibrium of  $X_{\underline{n}, A}$  if and only if  $(Aq)_i = (Aq)_j$  for all  $i, j \in \alpha$  and  $\alpha = 1, \dots, p$ .

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We call **diagonal matrix of type  $\underline{n}$**  to any diagonal matrix  $D = \text{diag}(d_i)$  s.t.  $d_i = d_j$  for all  $i, j \in \alpha$  and  $\alpha = 1, \dots, p$ .

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$$\begin{array}{c} \begin{array}{ccccc} & n_1 & \dots & n_\alpha & \dots & n_p \\ n_1 & \left[ \begin{array}{c|c|c|c|c} d_1 I_{n_1} & \dots & 0 & \dots & 0 \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ n_\alpha & 0 & \dots & d_\alpha I_{n_\alpha} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ n_p & 0 & \dots & 0 & \dots & d_p I_{n_p} \end{array} \right] \end{array} \end{array}$$

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A polymatrix game  $(\underline{n}, A)$  is called **conservative** if it has a formal equilibrium  $q$ , and there exists a positive diagonal matrix  $D$  of type  $\underline{n}$  s.t.  $Q_{AD} = 0$  on  $H_{\underline{n}}$ .

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## Proposition

If  $(\underline{n}, A)$  is conservative,  $q$  a formal equilibrium, and  $D$  a p.d.m. of type  $\underline{n}$  s.t.  $Q_{AD} = 0$  on  $H_{\underline{n}}$ , then

$$h(x) = - \sum_{i=1}^n \frac{q_i}{d_i} \log x_i$$

is a first integral for the flow of  $X_{\underline{n}, A}$ , i.e.,  $\dot{h} = 0$  along the flow of  $X_{\underline{n}, A}$ .

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is a first integral for the flow of  $X_{\underline{n}, A}$ , i.e.,  $\dot{h} = 0$  along the flow of  $X_{\underline{n}, A}$ . Moreover,  $X_{\underline{n}, A}$  is Hamiltonian w.r.t. a stratified Poisson structure on the prism  $\Gamma_{\underline{n}}$ , having  $h$  as its Hamiltonian function.

# Dissipative Polymatrix Replicators

## Definition

A polymatrix game  $(\underline{n}, A)$  is called **dissipative** if it has a formal equilibrium  $q$ , and there exists a positive diagonal matrix  $D$  of type  $\underline{n}$  s.t.  $Q_{AD} \leq 0$  on  $H_{\underline{n}}$ .

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## Proposition (Lyapunov function)

If  $(\underline{n}, A)$  is dissipative,  $q$  a formal equilibrium and  $D$  a p.d.m. of type  $\underline{n}$  s.t.  $Q_{AD} \leq 0$  on  $H_{\underline{n}}$ , then

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# Dissipative Polymatrix Replicators

## Proposition (Invariant Foliation)

Given a dissipative polymatrix game  $(\underline{n}, A)$ , if  $X_{\underline{n}, A}$  admits a formal equilibrium  $q$ , then there exists a  $X_{\underline{n}, A}$ -invariant foliation  $\mathcal{F}$  on  $\text{int}(\Gamma_{\underline{n}})$ .

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①

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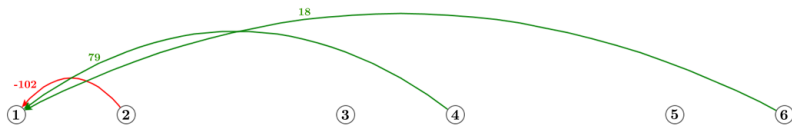
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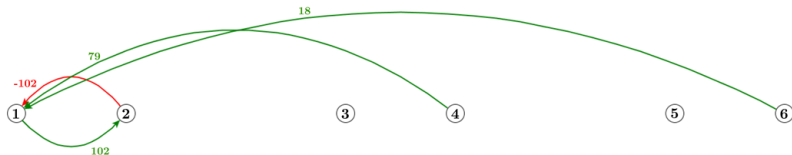
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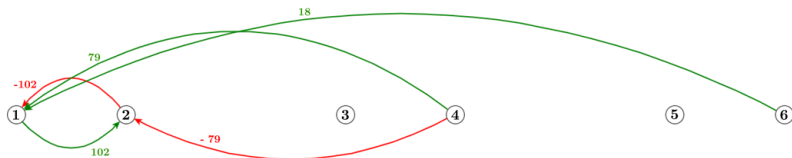




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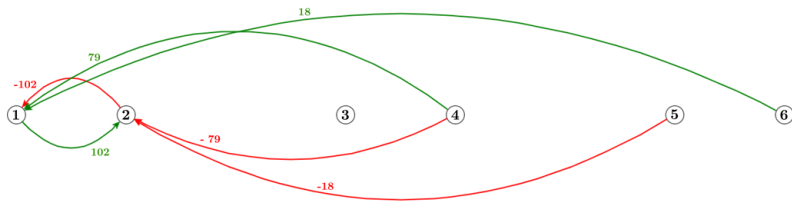
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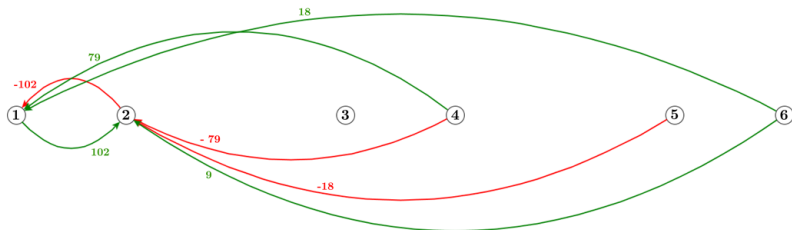
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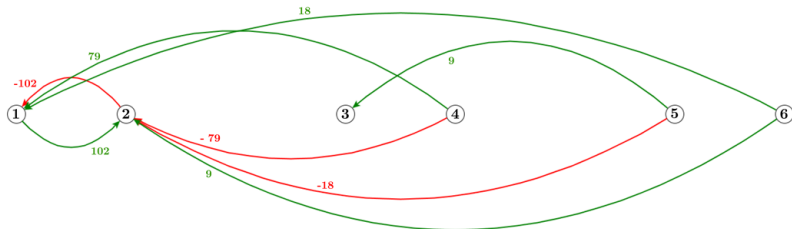
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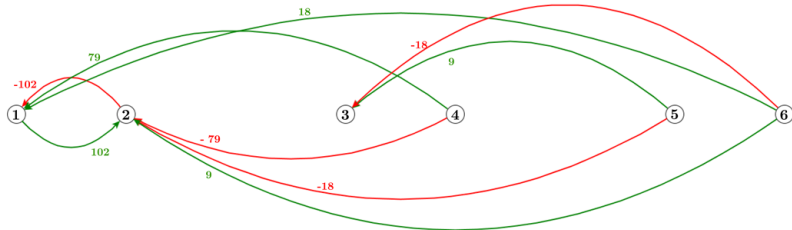
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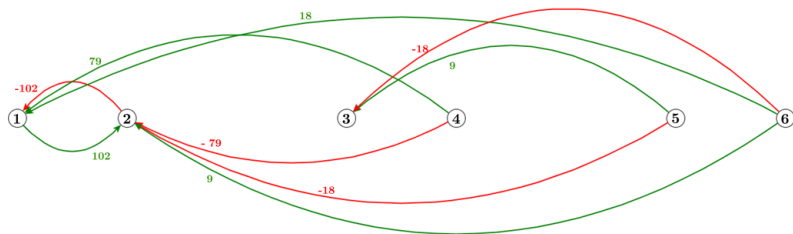
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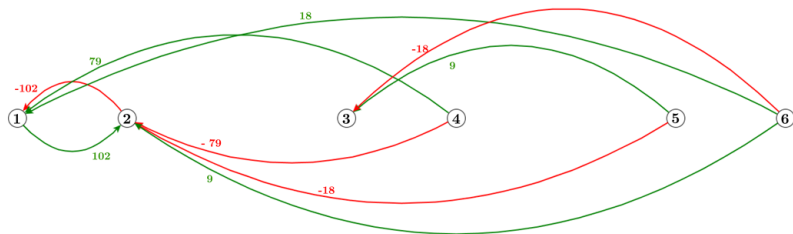


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Polymatrix game  $\mathcal{G} = ((2, 2, 2), A)$

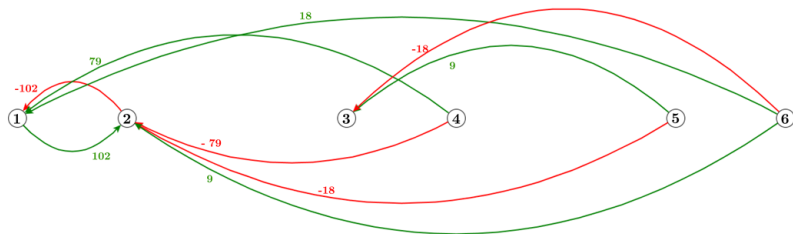
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Polymatrix game  $\mathcal{G} = ((2, 2, 2), A)$

$$A = \left[ \begin{array}{cc|cc|cc} 0 & -102 & 0 & 79 & 0 & 18 \\ 102 & 0 & 0 & -79 & -18 & 9 \\ \hline 0 & 0 & 0 & 0 & 9 & -18 \\ -51 & 51 & 0 & 0 & 0 & 0 \\ \hline 0 & 102 & -79 & 0 & -18 & -9 \\ -102 & -51 & 158 & 0 & 9 & 0 \end{array} \right].$$

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$X_{\mathcal{G}}$  vector field associated to the polymatrix replicator



## Polymatrix Game - Example State Space

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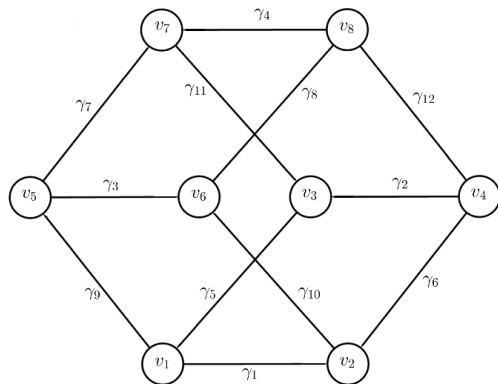


Figure: State space of  $\mathcal{G}$ .

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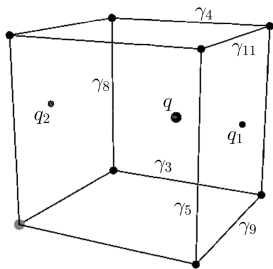


Figure: The equilibria of the associated polymatrix replicator of  $\mathcal{G}$ .

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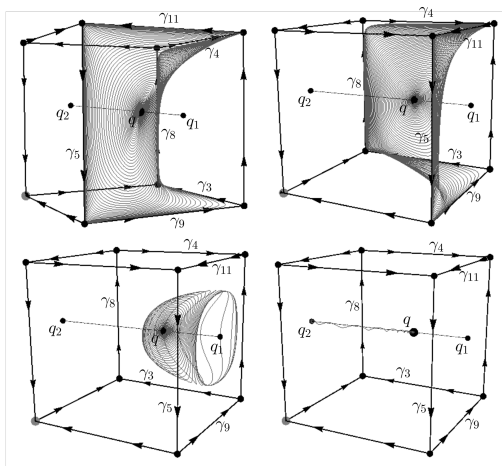
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By [Proposition \(Lyapunov Function\)](#), this system admits a strict global Lyapunov function

$$h : \text{int}(\Gamma_{(2,2,2)}) \rightarrow \mathbb{R}$$

for  $X_{\mathcal{G}}$ .

# Polymatrix Game - Example Dynamics



**Figure:** An approximation of the  $X_G$ -invariant manifold from two different perspectives (up), and two different orbits starting near the respective faces equilibrium (down).



# Bibliography

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- ▶ Alishah, H. N., Duarte, P., Peixe, T., *Asymptotic Poincaré maps along the edges of polytopes*, Submitted, (2015).
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